

Section 1.3

6.

$$\begin{aligned} -2x_1 + 8x_2 + x_3 &= 0 \\ 3x_1 + 5x_2 - 6x_3 &= 0 \end{aligned}$$

8. All vectors in \mathbb{R}^2 can be expressed as a linear combination of these particular \vec{u} and \vec{v} .

$$\begin{aligned} \vec{w} &= -\vec{u} + 2\vec{v} \\ \vec{x} &= -2\vec{u} + 2\vec{v} \\ \vec{y} &= -2\vec{u} + 3.5\vec{v} \\ \vec{z} &= 4\vec{u} + 3\vec{v} \end{aligned}$$

$$\begin{aligned} 11. \quad & \begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix} x_1 + \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} x_2 + \begin{bmatrix} 5 \\ -6 \\ 8 \end{bmatrix} x_3 = \begin{bmatrix} 2 \\ -1 \\ 6 \end{bmatrix} \\ & \begin{bmatrix} 1 & 0 & 5 & 2 \\ -2 & 1 & -6 & -1 \\ 0 & 2 & 8 & 6 \end{bmatrix} \xrightarrow{rref} \begin{bmatrix} 1 & 0 & 5 & 2 \\ 0 & 1 & 4 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \end{aligned}$$

The system of equations is consistent so \vec{b} must be a linear combination of \vec{a}_1 and \vec{a}_2 and \vec{a}_3 .

$$\begin{aligned} 12. \quad & \begin{bmatrix} 1 \\ -2 \\ 2 \end{bmatrix} x_1 + \begin{bmatrix} 0 \\ 5 \\ 5 \end{bmatrix} x_2 + \begin{bmatrix} 2 \\ 0 \\ 8 \end{bmatrix} x_3 = \begin{bmatrix} -5 \\ 11 \\ -7 \end{bmatrix} \\ & \begin{bmatrix} 1 & 0 & 2 & -5 \\ -2 & 5 & 0 & 11 \\ 2 & 5 & 8 & -7 \end{bmatrix} \xrightarrow{rref} \begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & \frac{4}{5} & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \end{aligned}$$

The system is inconsistent, \vec{b} cannot be a linear combination of \vec{a}_1 and \vec{a}_2 and \vec{a}_3 .

$$13. \quad \begin{bmatrix} 1 & -4 & 2 & 3 \\ 0 & 3 & 5 & -7 \\ -2 & 8 & -4 & -3 \end{bmatrix} \xrightarrow{rref} \begin{bmatrix} 1 & 0 & \frac{26}{3} & 0 \\ 0 & 1 & \frac{2}{3} & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

The system is inconsistent \vec{b} cannot be a linear combination of \vec{a}_1 and \vec{a}_2 and \vec{a}_3 .

$$14. \begin{bmatrix} 1 & -2 & -6 & 11 \\ 0 & 3 & 7 & -5 \\ 1 & -2 & 5 & 9 \end{bmatrix} \xrightarrow{rref} \begin{bmatrix} 1 & 0 & 0 & \frac{245}{33} \\ 0 & 1 & 0 & \frac{-41}{33} \\ 0 & 0 & 1 & \frac{-2}{11} \end{bmatrix}$$

The system of equations is consistent so \vec{b} must be a linear combination of \vec{a}_1 and \vec{a}_2 and \vec{a}_3 .

15.

$$\begin{aligned} 0\vec{v}_1 + 0\vec{v}_2 &= \vec{0} \\ -1\vec{v}_1 + 0\vec{v}_2 &= \begin{bmatrix} -7 \\ -1 \\ 6 \end{bmatrix} \\ 0\vec{v}_1 - 1\vec{v}_2 &= \begin{bmatrix} 5 \\ -3 \\ 0 \end{bmatrix} \end{aligned}$$

$$17. \begin{bmatrix} 1 & -2 & 4 \\ 4 & -3 & 1 \\ -2 & 7 & h \end{bmatrix} \xrightarrow{-4R_1+R_2 \rightarrow R_2} \begin{bmatrix} 1 & -2 & 4 \\ 0 & 5 & -15 \\ -2 & 7 & h \end{bmatrix} \xrightarrow{2R_1+R_3 \rightarrow R_3} \begin{bmatrix} 1 & -2 & 4 \\ 0 & 5 & -15 \\ 0 & 3 & h+8 \end{bmatrix} \xrightarrow{\frac{1}{5}R_2 \rightarrow R_2} \\ \begin{bmatrix} 1 & -2 & 4 \\ 0 & 1 & -3 \\ 0 & 3 & h+8 \end{bmatrix} \xrightarrow{-3R_2+R_3 \rightarrow R_3} \begin{bmatrix} 1 & -2 & 4 \\ 0 & 1 & -3 \\ 0 & 0 & h+17 \end{bmatrix}$$

To make the system consistent, $h \neq -17$. This would allow \vec{b} to be spanned by \vec{a}_1 and \vec{a}_2 .

19. $\text{Span}\{\vec{v}_1, \vec{v}_2\}$ a line made of multiples of \vec{v}_1 .

$$26. \quad \text{a.} \quad \begin{bmatrix} 2 & 0 & 6 & 10 \\ -1 & 8 & 5 & 3 \\ 1 & -2 & 1 & 3 \end{bmatrix} \xrightarrow{rref} \begin{bmatrix} 1 & 0 & 3 & 5 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Since the system is consistent, \vec{b} is in W .

$$\text{b.} \quad \begin{bmatrix} 2 & 0 & 6 \\ -1 & 8 & 5 \\ 1 & -2 & 1 \end{bmatrix} \xrightarrow{rref} \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

Since the system is consistent, the third column of A is in W .

Section 1.4

1. Undefined, the dimensions of the 3×2 matrix are incorrect for multiplying by a 3×1 matrix.
2. Undefined, the dimensions of the 2×1 matrix are incorrect for multiplying by a 2×1 matrix.

$$3. \quad 2 \begin{bmatrix} 6 \\ -4 \\ 7 \end{bmatrix} - 3 \begin{bmatrix} 5 \\ -3 \\ 6 \end{bmatrix} = \begin{bmatrix} 12 \\ -8 \\ 14 \end{bmatrix} + \begin{bmatrix} -15 \\ 9 \\ -18 \end{bmatrix} = \begin{bmatrix} -3 \\ 1 \\ -4 \end{bmatrix}$$

$$4. 1 \begin{bmatrix} 8 \\ 5 \end{bmatrix} + 1 \begin{bmatrix} 3 \\ 1 \end{bmatrix} + 1 \begin{bmatrix} -4 \\ 2 \end{bmatrix} = \begin{bmatrix} 7 \\ 8 \end{bmatrix}$$

Supplementary Exercises

$$5. \quad \text{a.} \quad \begin{bmatrix} 1 & 3 & k \\ 4 & h & 8 \end{bmatrix} \xrightarrow{-4R_1+R_2 \rightarrow R_2} \begin{bmatrix} 1 & 3 & k \\ 0 & h-12 & 8-4k \end{bmatrix}$$

Infinite Solutions : $h - 12 = 0$ and $8 - 4k = 0 \Rightarrow h = 12$ and $k = 2$

No solution : $h = 12$ and $k \neq 2$

One Solution : $h \neq 12$ and $k \in \mathbb{R}$

$$\text{b.} \quad \begin{bmatrix} -2 & h & 1 \\ 6 & k & -2 \end{bmatrix} \xrightarrow{3R_1+R_2 \rightarrow R_2} \begin{bmatrix} -2 & h & 1 \\ 0 & 3h+k & 1 \end{bmatrix}$$

Infinite Solutions : Not possible

No solution : $3h + k = 0 \Rightarrow k = -3h$

One Solution : $k \neq -3h$